The AUTEC array as a neutrino detector...

Neutrino Fishing in the Bahamas
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Many thanks to the US Navy and, in particular:

D. Belasco, J. Cecil, D. Deveau,
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An acoustic array in sea water is only sensitive to neutrinos (and showering muons) since the atmosphere stops all other species.

**Merit:** particle ID is automatic

**Liability:** (probably*) insensitive to the bulk of events

*Assuming the bulk of events are protons
Look for an existing very large hydrophone array with lattice density and frequency response matching the needs of UHE neutrino detection

This is non-trivial: most military arrays are built for surveillance (make sure enemy subs don’t come too close) So they are:

• sensitive at low frequency (~<100 Hz) because
  • subs produce mainly low frequency noise
  • high frequency noise does not propagate very far
• sparse (signals come from hundreds of km distance)
• very secret...
Atlantic Undersea Test and Evaluation Center

The largest USN high resolution, deep tracking array.
Tongue of the Ocean from space
Sheltered (islands and ~m deep shoals)

Deep (~1.5 km) volume of water

Tongue Of The Ocean

Very little shipping traffic

Several hydrophone arrays 4 shore stations
Deep sea in the "Tongue Of The Ocean"

Shallow bank off Andros Island
AUTEC Site 1 on Andros Island
Autec Site 3 (Bigwood Cay)
Range is large, helicopter is the favorite transportation (but boat is cheaper)
hydrophone subset used in the experiment (set up at Bahamas by J. Vandenbroucke)

hydrophone depths are 1550-1600 m
The 7-phone detector and sea floor

Distance North (m)  Distance East (m)
BAIL LIES DOWN WITH HYDROPHONE IN PLACE

~4.5 m
Autec phones are a good match to the problem but their lattice spacing in x, y, and z is too coarse to be optimal.
Very simple setup for cosmic-ray DAQ:

1. 1.7 GHz Pentium IV
2. Natl Inst sound card (digitize 7 channels at 179 kS/s)
3. Trigger/digital filter coded in LabView
4. 60 GB hot-swappable FireWire drive shipped back and forth to ferry data and program upgrades

Acquire 1 ms (179 Samples) for every event
Use adaptive threshold
Matched filter as an optimal detection algorithm in Gaussian noise

Matched filter technique is based on maximizing the likelihood of signal presence and uses the differences in noise spectrum and signal spectrum.

The matched filter which is used is a digital filter:

\[ Y_k = \sum H_i X_{k-i} \]
Present arrangement with the US Navy is very straightforward:

- Our DAQ is connected to their analog front-end via a multi-conductor cable
- During their tests they physically disconnect us

Overall 70% livetime is easy to obtain

- 16 months at the array
- 208 days livetime
- 25M triggers
- 350GB data
Status:

- Largest data-set ever collected being analyzed, paper expected in the near future (see Justin’s talk)

Future plans:

- Equip entire array (~60 phones and 250 km³)
- Possibly use new array (slightly larger with readout entirely at Site 1)
- Improve adaptive threshold algorithm
- Introduce 2-level trigger, with online coincidence detection
- GPS time in data stream
- Collaborators would be welcome!